## Dispersionless motion in a periodically rocked periodic potential

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Recently, dispersionless (coherent) motion of (noninteracting) massive Brownian particles, at intermediate time scales, was reported in a sinusoidal potential with a constant tilt. The coherent motion persists for a finite length of time before the motion becomes diffusive. We show that such coherent motion can be obtained repeatedly by applying an external zero-mean square-wave drive of appropriate period and amplitude instead of a constant tilt. Thus, the cumulative duration of coherent motion of particles is prolonged. Moreover, by taking an appropriate combination of periods of the external field, one can postpone the beginning of the coherent motion and can even have coherent motion at a lower value of position dispersion than in the constant tilt case.

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The inertial Brownian particle motion in periodic potentials [1,2] has been an archetypal model to theoretically understand many phenomena in physical systems. The currentvoltage characteristics of the resistively coupled shunted junction (RCSJ) model of Josephson junctions [3], the electrical conductivity of superionic solids [4], the motion of adatoms on the surface of a crystal [5], etc., are some of the important examples [1]. However, not all behaviors of the model particle motion in all time regimes are exhaustively investigated. A recent example being the discovery of dispersionless particle motion in a tilted periodic potential in the intermediate time regime by Lindenberg and co-workers [6]. During the coherent motion, the ensemble averaged position dispersion,  $\Delta x(t) = \langle (x(t) - \langle x(t) \rangle )^2 \rangle$ , remains constant.

This interesting phenomenon is shown (numerically) by particles moving on a cosinusoidal potential with a constant tilt (CT),  $F_0$ , in a medium with constant friction coefficient  $\gamma_0$  [6] in a limited ( $F_0$ ,  $\gamma_0$ ) region. The particles, after crossing the immediate barrier, move (after  $t = \tau_1 > \tau_K$ , the Kramers mean passage time) coherently with velocity  $v \approx F_0 / \gamma_0$ . The coherent motion continues until it is overwhelmed (at around  $t = \tau_2$ ) by the diffusive motion of the particles.  $\tau_1$  and  $\tau_2$  are specified only as a rough guide [6]. In this work we investigate the effect of a zero-mean square-wave (ZMSW) external drive F(t) of half period  $\tau$  and amplitude  $F_0$  instead of a CT.

The coherent motion, naturally, gets interrupted upon reversal of direction of F at  $t = \tau$  ( $\tau_1 < \tau < \tau_2$ ). Interestingly, as a main result of this work, the coherent motion once disturbed, by reversing the field at  $t = \tau$ , gets reestablished around  $t = \tau + \tau_1$  in almost the same form as it was during  $\tau_1 < t < \tau_2$  in the CT case. And this loss and subsequent recovery of coherent motion continue for a large number of reversals of F(t). The dispersion  $\Delta x(t)$ , however, increases rapidly during  $\tau < t < \tau + \tau_1$ . [During  $0 < t < \tau_1$ ,  $\Delta x(t) \sim t^{\alpha}$ , where  $\alpha \approx 2$ .]

We consider the motion of an ensemble of Brownian particles each of mass *m* moving in a potential  $V(x) = -V_0 \sin(kx)$  in a medium with friction coefficient [7]  $\gamma(x)$ 

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 $= \gamma_0 [1 - \lambda \sin(kx + \phi)]$  at temperature *T* (in units of  $k_B$ ) and subjected to an external force field *F*(*t*). The corresponding Langevin equation is given by [8]

$$m\frac{d^2x}{dt^2} = -\gamma(x)\frac{dx}{dt} + V_0k\cos kx + F(t) + \sqrt{\gamma(x)T}\xi(t), \quad (1)$$

where the Gaussian distributed zero-mean random forces  $\xi(t)$  satisfy  $\langle \xi(t)\xi(t')\rangle = 2\delta(t-t')$ .

Recalling the conductivity term in the "cos  $\phi$  problem" in the Josephson junction parlance, the friction coefficient  $\gamma(x)$ has an exact correspondence.  $\lambda$  in  $\gamma(x)$  is analogous to the ratio of conductivities associated with the Cooper-pair tunneling and the quasiparticle tunneling. The additional nonzero phase  $\phi$  in  $\gamma(x)$  is important. The phase difference  $\phi$ between potential V(x) and  $\gamma(x)$  introduces the required asymmetry in the otherwise spatially symmetric problem to obtain ratchet current. Note that the frictional nonuniformity does not affect the static equilibrium particle position distribution unlike in the case of temperature nonuniformity. Frictional inhomogeneity becomes effective only in the dynamic situation giving ratchet current [10,11].

For convenience we write down the Langevin equation in terms of dimensionless variables  $\bar{x}$ ,  $\bar{t}$ ,  $\bar{m}$ , etc. All these *barred* variables are written in terms of m,  $V_0$ , and k, for example,  $\bar{x}=kx$ ,  $\bar{t}=t\sqrt{V_0k^2/m}$ ,  $\bar{\gamma}_0=\gamma_0/k\sqrt{mV_0}$ ,  $\bar{T}=T/V_0$ ,  $\bar{\xi}=\xi(m/V_0)^{1/4}k^{-1/2}$ , etc. Omitting the *bars* over the dimensionless variables the resulting scaled Langevin equation becomes

$$\frac{d^2x}{dt^2} = -\gamma(x)\frac{dx}{dt} + \cos x + F(t) + \sqrt{\gamma(x)T}\xi(t), \qquad (2)$$

 $\xi(t)$  again satisfying  $\langle \xi(t)\xi(t')\rangle = 2\delta(t-t')$ .

The applied square-wave forces F(t) are taken as  $F(t) = \pm F_0$  for  $[2n\tau \le t < (2n+1)\tau]$  and  $F(t) = \mp F_0$  for  $[(2n + 1)\tau \le t < (2n+2)\tau]$  with n=0,1,2,... For constant applied force  $F(t)=F_0$  (for all *t*) the equation is solved using the matrix continued fraction method and also numerically, supporting each other quantitatively [1,9-12]. However, for finite  $\tau$ , the equation could be solved only numerically. The integration of the equation, using the fourth-order Runge-Kutta method [14], was carried out in time steps of  $\Delta t$ 

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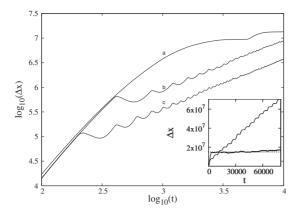


FIG. 1. The position dispersion  $\Delta x(t)$ 's for  $\tau$ =5000 (a), 400 (b), and 200 (c) are plotted. The inset shows curve (a) extended to 16 half periods together with the curve for the CT case. The dotted horizontal line is drawn to guide the eyes. Note that  $t_2 < 60\ 000$ .

=0.001. We choose to take  $\gamma_0$ =0.035. This is a typical value of friction where the system exhibits hysteresis [13].

We take  $\lambda = 0.9$  and  $\phi = 0.35$ .  $\lambda \neq 0$ , however, is relevant only while discussing ratchet current at the end. In fact, except for this minor point, all the results discussed in the following qualitatively remain the same for the simpler case of  $\lambda = 0$ .

The particles exhibit coherent motion in the potential  $V(x) = -\sin(x) - xF_0$  in the intermediate times roughly in the range  $\tau_1 (\approx 2 \times 10^3) < t < \tau_2 (\approx 3 \times 10^4)$  for  $F_0 = 0.2$ . Therefore, we choose the ZMSW field F(t) of amplitude  $F_0 = 0.2$  and, in most cases, half period  $\tau = 5000$  which is well within the range  $[\tau_1, \tau_2]$ . Naturally, in the first half period  $(0 < t \le \tau)$  the motion is the same as in the CT case. In all cases, we take the initial (t=0) particle position distribution as  $\delta(x-\frac{\pi}{2})$  and Maxwell velocity distribution corresponding to T=0.4. Note that after every half period  $\tau$  the periodic potential gets tilted in the reversed direction as a result of field reversal.

Curve (a) of Fig. 1 and its extended plot in the inset show that by applying the field, F(t), with  $\tau$ =5000, a repetitive sequence of trains of coherent motion, with characteristic constant  $\Delta x(t)$ , is obtained. These bursts of coherent motion are quite robust. Each burst of coherent motion is preceded by a length of dispersive particle motion. As a result  $\Delta x(t)$ grows, in discrete steps, with time, as the number *n* of half periods increases.

The generation of coherent motion continues for many  $(n \ge 8)$  half periods ( $\tau = 5000$ ) of F(t) (inset of Fig. 1). Thus, as an important consequence, the cumulative duration  $[\approx n(\tau - \tau_1)]$  of coherent motion when driven by F(t) is made much larger than the duration,  $\tau_2(\approx = 60\ 000) - \tau_1$ , achievable in the CT case as shown in the inset of Fig. 1.

In Fig. 1  $\Delta x$  corresponding to the half periods  $\tau$ =400 [curve (b)] and 200 [curve (c)] are also plotted. The important feature to be noticed in the figure is that for  $\tau$ =400,  $200 < \tau_K$ ,  $\tau_1$ ,  $\Delta x$  dips immediately after the field is reversed before it rises. This behavior of dispersion dipping and subsequent rise becomes most pronounced at a small but intermediate  $\tau$ . It continues for many periods of F(t).

Figure 2 summarizes the main results of this work. It

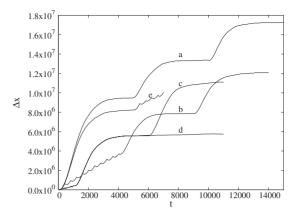


FIG. 2.  $\Delta x(t)$ 's for three  $\tau$ =5000 (a), ten  $\tau$ =400 and two  $\tau$ =5000 (b), five  $\tau$ =200 and two  $\tau$ =5000 (c), five  $\tau$ =200 and one  $\tau$ =10 000 (d), and one  $\tau$ =5000 and five  $\tau$ =400 (e) half periods are plotted.

shows many interesting effects of taking few initial half periods of F(t) of smaller duration,  $\tau$ =400 [curve (b)] and  $\tau$ =200 [curves (c) and (d)], and then making its later half periods  $\tau$ =5000 or larger [e.g., 10 000; curve (d)]. Curves (b) and (c) show that, in this case too, during the later half periods  $\tau$ =5000 of F(t), a similar sequence of trains of coherent motion, as in Fig. 1, inset [or curve (a)], can be obtained. It also allows us to postpone [curve (b)] the appearance of coherent motion beyond  $t=\tau_1$ . Moreover, it is possible to obtain coherent motion with lower constant dispersion [curves (c) and (d)] than in the CT case [i.e., lower than the constant  $\Delta x$  in the first half period in curve (a)] too. Curve (e) shows that curves (b)–(d) can be repeated, using the same customized procedure, many times over again.

The results of Figs. 1 and 2 can be understood by analyzing the time evolution of velocity distribution, P(v). P(v)'s at various phases of F(t) at  $t=5\tau$  and  $t=\tau+15.6$  for  $\tau$ = 5000 and at  $t=2\tau$  and  $t=2\tau+16$  for  $\tau=1000$  are shown in Fig. 3. P(v) invariably assumes almost a Gaussian form of same width and centered at a fixed  $v \approx \pm F_0 / \gamma_0$  at  $t=n\tau$  for  $\tau=5000$ . The inset, showing the mean velocity  $\overline{v}(t)$  and ve-

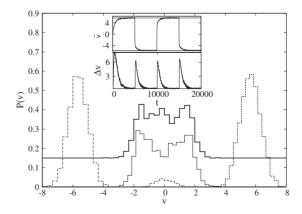


FIG. 3. P(v)'s at  $t=25\ 000$  (right peak) and 25\ 015.6 (middle thin line) for  $\tau=5000$  and at t=2000 (bimodal, dashed-dotted) and 2016 (middle bold line shifted vertically by 0.15) for  $\tau=1000$ .  $\overline{v}(t)$  and  $\Delta v(t)$  for  $\tau=5000$  are plotted ( $\overline{v}=\pm F_0/\gamma_0$  lines drawn) in the inset.

TABLE I. The systems considered are (1) Ag, Ag on AgI lattice, (2) MM, a macromolecule along a polymer, and (3) JJ, Josephson junction. The symbols have their usual meaning. The RCSJ-model JJ equation is equivalent to Eq. (2.1) in [3]:  $\frac{\hbar C}{2e}(d^2\theta/dt^2) + \frac{\hbar}{2e}G[1 + \lambda \cos(\theta + \phi)]\frac{d\theta}{dt} + I_1 \sin(\theta) = I(t) + \sqrt{2TG[1 + \lambda} \cos(\theta + \phi)]\xi(t)$ . (Add  $-\frac{\pi}{2}$  to  $\theta$  for exact correspondence.)

	<i>m</i> (kg)	$V_0$ (eV)	T (K)	$k ({\rm m}^{-1})$	$\omega_0 (s^{-1})$	$\gamma_0 ~(\mathrm{kg~s^{-1}})$	$\frac{\gamma_0}{m}$ (s <sup>-1</sup> )	$F_0$ (n)	$ au\left(\mathrm{s} ight)$	$\overline{v} = \frac{F_0}{\gamma_0} (\mathrm{ms}^{-1})$
U	$1.79 \times 10^{-25}$ $3.32 \times 10^{-22}$		348 300			$2.55 \times 10^{-14} \\ 7.21 \times 10^{-14}$				$\begin{array}{c} 1.48 \times 10^{3} \\ 4.51 \times 10 \end{array}$
	<i>C</i> (pF)	$I_1$ (A)	T (mK)	$\frac{2e}{\hbar}$ (V <sup>-1</sup> s <sup>-1</sup> )	$\omega_P (s^{-1})$	$G \ (\Omega^{-1})$	$\omega = \frac{G}{C} (s^{-1})$	$I_0$ (A)	$ au\left(\mathrm{s} ight)$	$\overline{V} = \frac{I_0}{G} (\mathbf{V})$
JJ	0.5	10 <sup>-9</sup>	9.53	$3.038 \times 10^{15}$	$2.46 \times 10^{9}$	$4.31 \times 10^{-5}$	$8.63 \times 10^{7}$	$2.0 \times 10^{-8}$	$2.03 \times 10^{-6}$	$4.64 \times 10^{-4}$

locity dispersion  $\Delta v(t)$ , supports this observation. However, at  $t=n \times 1000$ , P(v) has two peaks, one centered at  $v \approx \pm F_0/\gamma_0$  and the other at v=0.

The P(v) peak at v=0 shows that at  $t=n\tau$ , for  $\tau < \tau_1$ , some particles are left behind in the locked state in one or some other wells. The smaller the  $\tau$  is, the more prominent this latter peak is left at  $t=\tau$ . These locked particles try to gravitate to their respective well bottoms and, being slower, even succeed in shrinking the position distribution P(x) more effectively than the much faster particles in the running state on the front. Thus, for smaller  $\tau < \tau_1$ , the bimodal nature of P(v) helps appreciable  $\Delta x$  dipping immediately after field reversal (Fig. 1).

At  $t=n\tau+t_0$ ,  $15 < t_0 < 16$ ,  $\bar{v}$  becomes zero for all  $\tau$  and n. (It turns out,  $2t_0 \approx 1/\gamma_0$ , the frictional relaxation time.) The corresponding P(v)'s are also shown in Fig. 3. For  $\tau=5000$ , P(v) at  $t=n\tau+t_0$  is like a sum of two "Gaussians" centered on either side of v=0. But for  $\tau=1000$ , the surviving P(v) peak at v=0 at  $t=n\tau$  contributes an additional one centered at v=0, making  $\bar{v}=0$  at the same delay time  $\tau_0$ .

Due to the tilt direction reversal the particles, in the running state, are forced to reverse their direction of motion and hence each of them necessarily goes through zero velocity at least once momentarily. Thus, the entire system passes approximately through a "thermal" state at  $t=n\tau+\tau_0$ . Hence, after every field reversal at  $t=n\tau$  the particles begin their subsequent journey in the reversed direction with almost the same delayed initial condition (at  $t=n\tau+\tau_0$ ) of thermalized P(v). Therefore,  $\Delta x$ 's are expected to behave similarly after every  $n\tau$ .

As discussed above, it is just the reversal of field which leads P(v) to the required form at  $t=n\tau+t_0$ , irrespective of the form of P(v) at  $t=n\tau$  for any value of  $\tau \ge \tau_0 \approx 16$ . It shows that in order to obtain coherent motion neither an exact initial Gaussian velocity distribution is necessary nor all the particles are required to be initially confined sharply to a single well bottom of the periodic potential. Also, mere switching the field alternately on  $(F_0 \neq 0)$  for duration  $\tau$  and off  $(F_0=0)$  for the same duration  $\tau$  fails to yield results like those in Figs. 1 and 2. This indicates that a reversal of the field direction is essential because this alone ensures a "thermalized" P(v).

It must also be noted that during the CT case the average particle displacement is large,  $\approx \tau_2 F_0 / \gamma_0$ , by the end of its coherent motion, whereas in the ZMSW case it is zero for  $\lambda=0$  and small and finite for  $\lambda \neq 0$  and  $\phi \neq 0, \pi$  after any

large time  $t=2n\tau$ . This is an added practical advantage over the CT case for, in the ZMSW case, most of the particles on the average remain confined to a finite region of space despite periodically showing coherence of motion for a long time.

The dimensionless values of parameters used (e.g.,  $\gamma_0$ =0.035, T=0.4,  $\tau$ =5000, and F<sub>0</sub>=0.2) and other derived quantities when restored to their usual units are presented in Table I for three illustrative cases: (i) the motion of a Ag ion in AgI crystal [15], (ii) the motion of a macromolecule (kinesin) along a polymer fiber (microtubule) [16], and (iii) diffusion of Cooper pairs across a Josephson junction [3]. Notice that  $\omega(=\gamma_0/m) \ll \omega_0$  in the particle motion case and  $\omega \ll \omega_P$  in the Josephson plasma frequency  $(=2eI_1/\hbar C)$ , showing that the systems considered are, indeed, underdamped. The last column of Table I gives the magnitude of mean velocity (mean voltage) attained during the coherent state when the initial value of the drive field F(t) [I(t)] is fixed either at  $+|F_0|$  ( $+|I_0|$ ) or with their sign reversed and not an equal mixture of both. Also, during the half period  $\tau$  the particles move to an average distance (the product of quantities in the last two columns) of the order of a micron  $(\mu)$ which will get retraced in the next half period. This gives a rough idea of the sample size one would need to take in a ZMSW case. Also,  $\frac{2\pi}{\tau} \ll \omega_0(\omega_P)$  (by about two orders of magnitude).

The calculated average velocities  $\overline{v}$  and velocity dispersions  $\Delta v$  are plotted in the inset of Fig. 3. An equal mixture of  $F(t=0)=\pm |F_0|$  makes  $\overline{v}$  close to zero during coherent motion. It is exactly zero for  $\lambda=0$  at all t and hence even in the limit  $t \rightarrow \infty \overline{v}$  remains zero. However, for  $\lambda \neq 0$  and  $\phi \neq 0, \pi$  a nonzero finite mean (steady state) velocity is obtained [10–12] earlier. The contribution of coherent particle motion being insignificant, the dispersive motion alone contributes to this *ratchet* current of particles.

The diffusion constant, *D*, defined as  $\lim_{t\to\infty} \Delta x(t) = 2Dt$ , is hard to calculate for a constant tilt  $F_0$  [6]. The asymptotic limit barely reaches even by  $t=10^7$ . However, for ZMSW this limit is readily reached by  $t=10^7$  (Fig. 4). It may be noted that for each curve in Figs. 1 and 2 we have averaged over 2000 realizations, but in Fig. 4 we could average over number of realizations ranging only between 18 and 60. The nature of  $\Delta x(t)$  so clear in Fig. 1 appears less convincing in Fig. 4. Therefore, it is hard to conclude that the same nature of  $\Delta x$ , as in Fig. 1, will continue until the asymptotic time regime. However, from the thermalized P(v) argument given

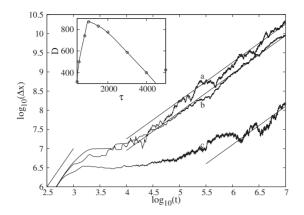


FIG. 4.  $\Delta x(t)$ 's for  $\tau$ =1000 (a), 5000 (b), and the case of CT  $F_0$ =0.2 (c) averaged over 20, 60, and 18 ensembles, respectively, are plotted. Lines of slope 1 are fitted to the curves. The short line at the lower left corner indicates  $\Delta x \sim t^{\alpha}$ , where  $\alpha \approx 2$ . The inset shows variation of D with  $\tau$ .

earlier, there is a fair likelihood that the nature of  $\Delta x(t)$  shown in Fig. 1 will extend to a large number of half periods of F(t) provided a large number of particles are considered for averaging.

The nature of  $\Delta x(t)$  shown by the curves in Figs. 1 and 2 is in no finite region close to  $\Delta x(t) \sim t$ . It remains, therefore, open to explain why a large number of repeatedly same diverse combinations of dispersions such as ones ranging from  $\Delta x(t) \sim t^2$  to  $\Delta x(t) \sim t^0$ , when averaged over a large number of realizations yield the same nature of dispersion,  $\lim_{t\to\infty} \Delta x(t) \sim t$ , for all  $\tau$  (Fig. 4).

 $D(\tau)$ 's, plotted in the inset of Fig. 4, are rough estimates as the averagings are done only over a small number of realizations. However, the overall qualitative trend of  $D(\tau)$  remains valid.  $D(\tau)$  shows a peak around  $\tau = \tau_1$ . For  $\tau > \tau_1$ , the closer the  $\tau$  is to  $\tau_1$  the smaller the constant  $\Delta x$  region is and hence larger is the fraction of sharply rising  $\Delta x$  region is. Naturally total  $\Delta x$  will be larger as  $\tau \rightarrow \tau_1$ . However, the nature of  $D(\tau)$  as  $\tau \rightarrow \tau_2$  is not clear from the available data. In the range  $\tau < \tau_1$ ,  $\Delta x$  rises only after an appreciable dipping (Fig. 1). Therefore, the initial rise of  $\Delta x$  is slower as  $\tau$  is decreased from  $\tau_1$  resulting in a smaller total  $\Delta x(t)$  as  $t \rightarrow \infty$  and hence smaller *D*.

From the rms spread ( $\sqrt{\Delta x}$ ) point of view the advantage of ZMSW F(t) over CT, except in cases like curve (d) in Fig. 2, quickly evaporates as t increases. Whereas for the CT case at  $t=10\tau=5\times10^4$ , the mean displacement  $\bar{x}$  is  $2.8\times10^5$  and  $\sqrt{\Delta x}$  is  $0.22\times10^5$  and at  $t=2000\tau=10^7$ ,  $\bar{x}=5.7\times10^7$  and  $\sqrt{\Delta x}=0.012\times10^7$ , for the ZMSW case, at  $t=10\tau$ ,  $\bar{x}\approx0$  and  $\sqrt{\Delta x}=0.06\times10^7$ , and at  $t=10^7$ ,  $\bar{x}\approx0$  and  $\sqrt{\Delta x}=0.095\times10^7$ . Perhaps in the ZMSW case, the particles left behind during a  $\tau$  get pushed father away during the next  $\tau$  and make the  $\sqrt{\Delta x(t)}$  increase faster as t increases.

Coherent motion is observed only in the negative slope region of  $D(\tau)$ . However, for this same system it is shown in Ref. [12] that ratchet current is maximum for a value of  $\tau \approx 500$ , i.e., in the rising  $D(\tau)$  region, and becomes significantly small for larger  $\tau \ge \tau_1$  and almost zero at  $\tau = 5000$ . The peak of the  $D(\tau)$ , thus, roughly divides  $\tau$  into two regions: (i) small  $\tau$  giving ratchet current and (ii) larger  $\tau$  showing coherent motion.

To summarize, the dispersionless (coherent) motion discovered earlier, to occur for a brief but finite duration in the intermediate time regime, on a CT sinusoidal potential, was extended to the case of periodically reversing constant tilts. We have shown the possibility of obtaining coherent particle motion interspersed by dispersive motion over many periods of an external ZMSW field. The cumulative duration of coherent motion can, thus, be extended to a substantial fraction of the total journey time, of course, at a cost of making the system several times more diffusive.

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